# Green Journals

International Approved Journals

## Journal Information

| | |
|---|---|
| **Journal Title** | Russian Journal of Nonlinear Dynamics |
| **Publisher** | Institute of Computer Science Izhevsk |
| **ISSN** | 2658-5324 |
| **E-ISSN** | 2658-5316 |
| **Database** | SCOPUS |
| **Domain** | Physical Sciences |

## Classification History

| Year | A+ | A | B | C |
|---|---|---|---|---|
| **2026** | | | ✓ | |
| **2025** | | | ✓ | |
| **2024** | | | ✓ | |
| **2023** | | | ✓ | |
| **2021/2022** | | | ✓ | |
| **2020** | | | ✓ | |
| **2019** | | | | |
| **2018** | | | | |

**Classification:** The table above shows all journal classifications recorded for each classification year in the Green Journals database. A journal may have more than one classification in the same year.

## Recent Articles

**$C^{1}$-Smooth Skew Products on a $3D$-Torus Which Have an $\Omega$-Stable Quotient and Continuous Itinerary Auxiliary Multifunctions**
2026 Vol. 22 Issue 2 Pages 437-468
Authors: L. S. Efremova
DOI: 10.20537/nd260401

**An Improved Approach for Numerically Estimating the Dimension of Inertial Manifolds in Infinite-Dimensional Dynamical Systems**
2026 Vol. 22 Issue 2 Pages 389-402
Authors: P. V. Kuptsov
DOI: 10.20537/nd260308

**A Case of Nonexistence of Generalized Pseudo-Anosov Homeomorphisms with One Needle on a Closed Nonorientable Surface of Genus 3**
2026 Vol. 22 Issue 2 Pages 415-426
Authors: A. A. Medvedev, A. Yu. Zhirov
DOI: 10.20537/nd260404

**Robust Accelerated Iterative Learning Control Design for Discrete-Time Systems with Input Saturation**
2026 Vol. 22 Issue 3 Pages 677-692
Authors: P. V. Pakshin, J. P. Emelianova, M. A. Emelianov
DOI: 10.20537/nd260904

**On Normal Forms of Reversible Systems with Lorenz Attractors and Repellers**
2026 Vol. 22 Issue 2 Pages 333-349
Authors: A. S. Gonchenko, S. V. Gonchenko, K. N. Trifonov
DOI: 10.20537/nd260501

**Robust Path Tracking Control of an Unmanned Eight-Wheeled Off-Road Vehicle in the Presence of Wheels' Slipping**
2026 Vol. 22 Issue 1 Pages 223-243
Authors: K. A. Iakushkov, A. S. Matveev
DOI: 10.20537/nd260312

**Erratum to: Stabilization of a Spherical Robot with an Internal Pendulum During Motion on an Oscillating Base**
2026 Pages 0-0
Authors: A. V. Klekovkin, Yu. L. Karavaev, A. V. Nazarov
DOI: 10.20537/nd261002

**Prototype of a Bionic Prosthesis Sensory Feedback System**
2026 Vol. 22 Issue 1 Pages 213-222
Authors: A. A. Miklin, P. M. Ryabkova, D. I. Strokov et al.
DOI: 10.20537/nd260303

**An Example of Robust Orbital Stabilization of a Periodic Behavior: Subspace and Sliding-Mode-Based Stabilization of Transverse Linearization**
2026 Vol. 22 Issue 1 Pages 5-26
Authors: L. B. Freidovich, P. E. Aleshin, A. S. Shiriaev et al.
DOI: 10.20537/nd260313

**Special Issue "Modern Problems of Robotics and Control Theory" An Introductory Note**
2026 Vol. 22 Issue 1 Pages 3-4
DOI: 10.20537/nd260315