Green Journals

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Journal Information

Journal Title	Intelligent Service Robotics
Publisher	
ISSN	1861-2776
E-ISSN	
Database	AERES
Domain	Health Sciences, Physical Sciences, Social Sciences

Classification History

Year	A+	A	B	C
2026		✓	✓	
2025		✓	✓	
2024		✓	✓	
2023		✓	✓	
2021/2022		✓	✓	
2020		✓	✓	
2019		✓	✓	
2018		✓		

Classification: The table above shows all journal classifications recorded for each classification year in the Green Journals database. A journal may have more than one classification in the same year.

Recent Articles

A digital twin-enabled environment for end-user development of robot tasks
2026-10-28 Vol. 19 Issue 6
Authors: Luigi Gargioni, Daniela Fogli, Elena Margherita Nava
DOI: 10.1007/s11370-026-00758-7

A study on the effects of mixed explicit and implicit communications in human-artificial-agent interactions
2026-10-28 Vol. 19 Issue 6
Authors: Ana Christina Almada Campos, Bruno Vilhena Adorno
DOI: 10.1007/s11370-026-00755-w

Hierarchical multimodal driven humanoid robot decision making framework for dynamic human–machine environment
2026-10-26 Vol. 19 Issue 6
Authors: Zhenyu Qiu, Xiaojun Tang
DOI: 10.1007/s11370-026-00762-x

Ranked behavior cloning for productivity-driven imitation learning with zone-based safety modulation in human–robot collaborative tasks
2026-10-20 Vol. 19 Issue 6
Authors: Pranav Rajesh Nair, Abhra Roy Chowdhury
DOI: 10.1007/s11370-026-00761-y

Gait-parameterized RL for locomotion across morphologies and scales without reward retuning
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Authors: Sungho Lee, Jungyeong Kim, Sangshin Park et al.
DOI: 10.1007/s11370-026-00759-6

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DOI: 10.1007/s11370-026-00757-8

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2026-9-30 Vol. 19 Issue 6
Authors: Luyang Han, Bing Liang, Jiangtao Lv et al.
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DOI: 10.1007/s11370-026-00754-x

Motion control of an aquatic snake robot with actuator failures and environmental uncertainties using neural network super twisting sliding mode control
2026-9-24 Vol. 19 Issue 6
Authors: Bhavik M. Patel, Roberto G. Valenti, Santosha K. Dwivedy
DOI: 10.1007/s11370-026-00753-y

C2f-space: coarse-to-fine space grounding for spatial instructions using vision-language models
2026-9-16 Vol. 19 Issue 6
Authors: Nayoung Oh, Dohyun Kim, Junhyeong Bang et al.
DOI: 10.1007/s11370-026-00729-y