Green Journals

International Approved Journals

Journal Information

Journal Title	Journal of Field Robotics
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Database	SCOPUS
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Classification History

Year	A+	A	B	C
2026		✓	✓	
2025		✓	✓	
2024		✓	✓	
2023		✓	✓	
2021/2022		✓	✓	
2020		✓	✓	
2019		✓	✓	
2018		✓		

Classification: The table above shows all journal classifications recorded for each classification year in the Green Journals database. A journal may have more than one classification in the same year.

Recent Articles

Merging Reaction to Cognition: A Hybrid Cognitive Strategy for Odor Source Localization in Natural Environments
2026-10-29
Authors: Hugo Magalhães, Rui Baptista, Lino Marques
DOI: 10.1002/rob.70375

Acoustic–Visual Sensor Fusion for Robot Localization in Buried Pipes
2026-10-23
Authors: Rob Worley, Yicheng Yu, Kirill V. Horoshenkov et al.
DOI: 10.1002/rob.70368

A Cooperative Area Allocation and Adaptive Coverage Planning Method for Multi-AUV Underwater Search and Rescue
2026-10-23
Authors: Zhou Nan, Lin Zhou, Zhongben Zhu et al.
DOI: 10.1002/rob.70372

Drift-Corrected Monocular VIO and Perception-Aware Planning for Autonomous Drone Racing
2026-10-21
Authors: Maulana Bisyir Azhari, Donghun Han, Je In You et al.
DOI: 10.1002/rob.70371

A Modular Vision-Based Robot for Efficient Noninvasive Inspection of External Pipeline Surfaces
2026-10-21
Authors: Steve James, R. Ambigai
DOI: 10.1002/rob.70365

A Perception-Aware Hierarchical Planning Framework for Multi-Target Substation Inspection With UAVs
2026-10-19
Authors: Jiulong Wang, Jian Di, Wen Wang et al.
DOI: 10.1002/rob.70359

Bridging the Sim2Real Gap: Multi-Fidelity Reinforcement Learning for Autonomous Surface Vehicles
2026-10-19
Authors: Maria Inês Pereira, Daniel Filipe Campos, Andry Maykol Pinto
DOI: 10.1002/rob.70370

Context-Aware Reconstruction for DVL Outlier Detection in Robust AUV Navigation
2026-10-13
Authors: Xin Zhang, Shaolei Li, Bo He et al.
DOI: 10.1002/rob.70369

DR-ICP: Robust LiDAR SLAM Registration for Degenerate Tunnels
2026-10-12
Authors: Guanyu Qian, Xuemei Chen, Chao Lu et al.
DOI: 10.1002/rob.70362

OP-Follower: Onboard Vision-Based Obstacle-Aware Predictive Person Following for Quadruped Robots via IBVS-NMPC Control
2026-10-12
Authors: Junwei Ge, Xinlong Miao, Jinya Su et al.
DOI: 10.1002/rob.70363