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Journal Information

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Classification History

Year	A+	A	B	C
2026		✓	✓	
2025		✓	✓	
2024		✓	✓	
2023		✓	✓	
2021/2022		✓	✓	
2020		✓	✓	
2019		✓	✓	
2018		✓		

Classification: The table above shows all journal classifications recorded for each classification year in the Green Journals database. A journal may have more than one classification in the same year.

Recent Articles

Multi-view context-consistent image reconstruction for building facades
2026-10-29 Pages 1-18
Authors: Fuad Hasan, Chul Min Yeum, Huaiyuan Weng et al.
DOI: 10.1080/01691864.2026.2749260

R-Metaverse: multimodal social cues for real-world-centered telepresence-MR collaboration with telepresence robots
2026-10-29 Pages 1-19
Authors: Yuhi Nishikori, Yuya Hosoda, Joo-Ho Lee
DOI: 10.1080/01691864.2026.2743361

Flexible-torso quadruped robots: biomimetic principles, structural designs, and torso-limb coordination – a review
2026-10-23 Pages 1-33
Authors: Runze Yu, Binghui Wu
DOI: 10.1080/01691864.2026.2742578

Generalising series elastic actuation to flexible-link flexible-joint robot control using end-point position sensing
2026-10-21 Pages 1-16
Authors: Xavier Garant, Clément Gosselin
DOI: 10.1080/01691864.2026.2749313

Anti-slip power-assist for electric carts via switched force and slip-acceleration control for responsive assistive motion
2026-10-21 Pages 1-15
Authors: Juan Padron, Hirotaka Kitagawa, Taiga Hoshino et al.
DOI: 10.1080/01691864.2026.2743350

Synergizing physical and cognitive training toward active aging with mixed reality

2026-10-15 Pages 1-14

Authors: Filippo Favali, Marta Gabbi, Lorenzo Sabattini et al.

DOI: 10.1080/01691864.2026.2731666

Dynamic properties and motion reproducibility of a compact pneumatically actuated humanoid upper body for data-driven control

2026-10-15 Pages 1-20

Authors: Hiroshi Atsuta, Hisashi Ishihara, Minoru Asada

DOI: 10.1080/01691864.2026.2736439

Correction

2026-10-9 Pages 1-1

DOI: 10.1080/01691864.2026.2740354

Polygonal proximity map: a compact free-space representation for efficient path planning with minimal geometric information

2026-10-9 Pages 1-19

Authors: Rikuto Nonomura, Yuichi Tazaki, Yasuyoshi Yokokohji

DOI: 10.1080/01691864.2026.2737559

Growing a humanoid controller continuously: unified multi-skill control on top of a stable locomotion substrate

2026-10-7 Pages 1-24

Authors: Zhen Xu, Jianan Xie, Hongming Chen et al.

DOI: 10.1080/01691864.2026.2742586